



西安电子科技大学  
XIDIAN UNIVERSITY

# MSSDet: A Multi-scale Ship Detection Framework in Optical Remote Sensing Images



**Speaker: Weiming Chen**

**2021-10-28**

**Visual Information in Processing Lab(VIP Lab)**



- Introduction
- HRSC2016-MS Dataset
- MSSDet
- Experimental Result
- Conclusion



- Introduction
- HRSC2016-MS Dataset
- MSSDet
- Experimental Result
- Conclusion



**Fishery management**



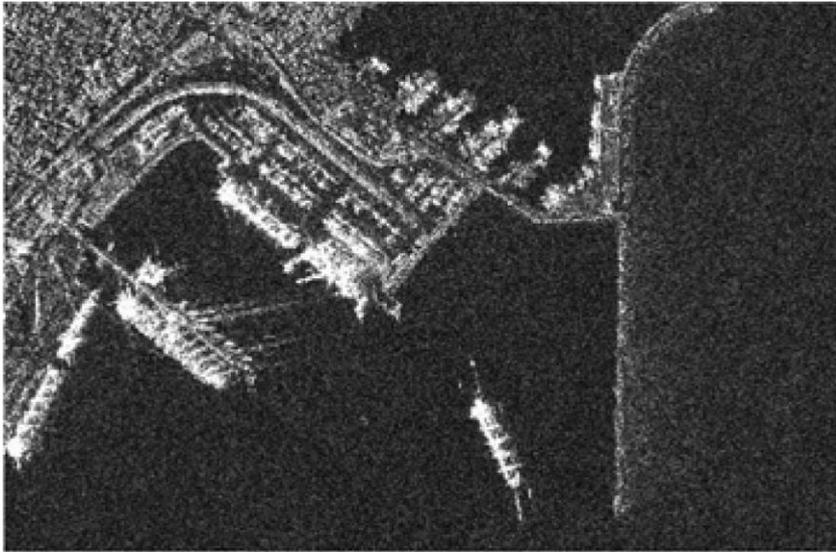
**Suppress smuggling**



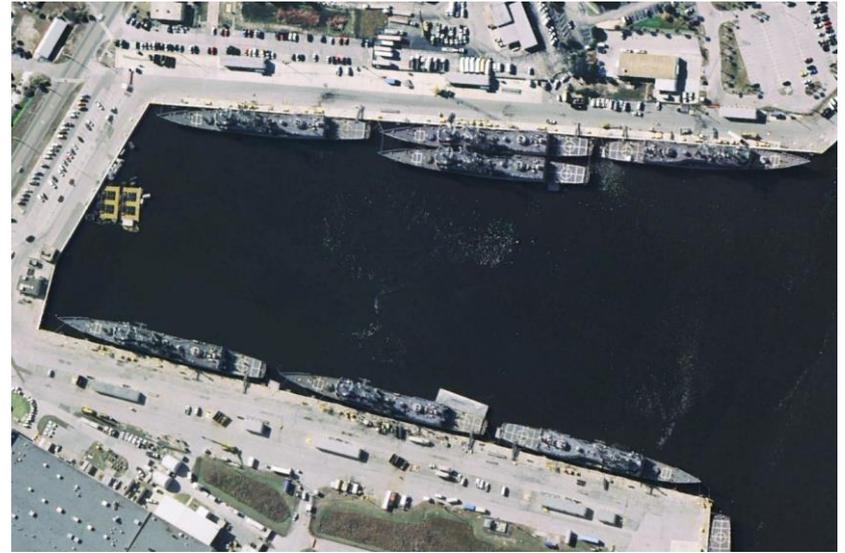
**Maritime transportation**



**Naval warfare**



**Synthetic Aperture Radar (SAR)**



**Optical Remote Sensing (ORS)**



Dataset	Categories	Images	Instances	Year
TAS	1	30	1319	2008
SZTAKIINRIA	1	9	665	2012
*NWPU VHR10	10	800	3775	2014
VEDAI	9	1210	3640	2015
UCASAOD	2	910	6029	2015
DLR 3K Vehicle	2	20	14235	2015
*HRSC2016	1	1070	2976	2016
RSOD	4	976	6950	2017
*DOTA	15	2806	188282	2018
*DIOR	20	23463	192472	2019
*HRRSD	13	26722	55740	2019

\*: the dataset contains the category of ship.



**Method**

**Advantages**

**Disadvantages**

Non-oriented Ship  
Detection

High accuracy;  
Strong robustness

Cannot predict orientation;  
Weak detection performance for  
dense objects

Oriented Ship Detection

Can predict orientation;  
Good detection performance  
for dense objects

Hard to annotate;  
Low efficiency



**Non-oriented Ship Detection**



**Oriented Ship Detection**



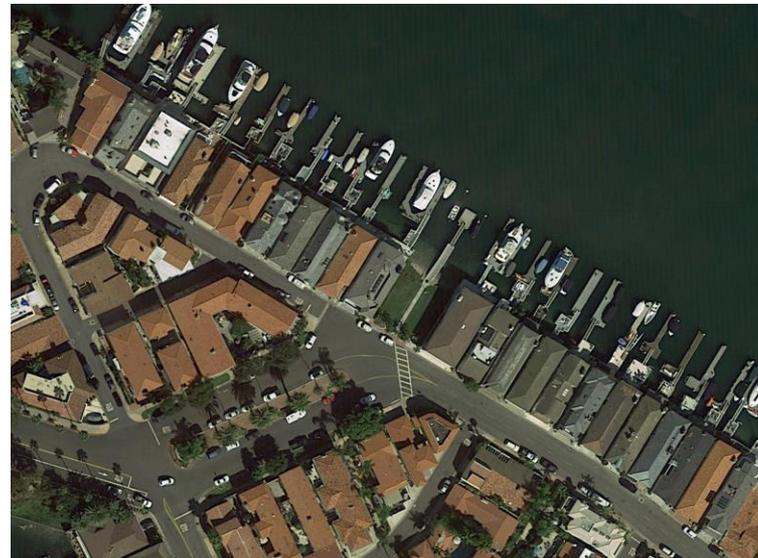
## Natural Image



Moderate size

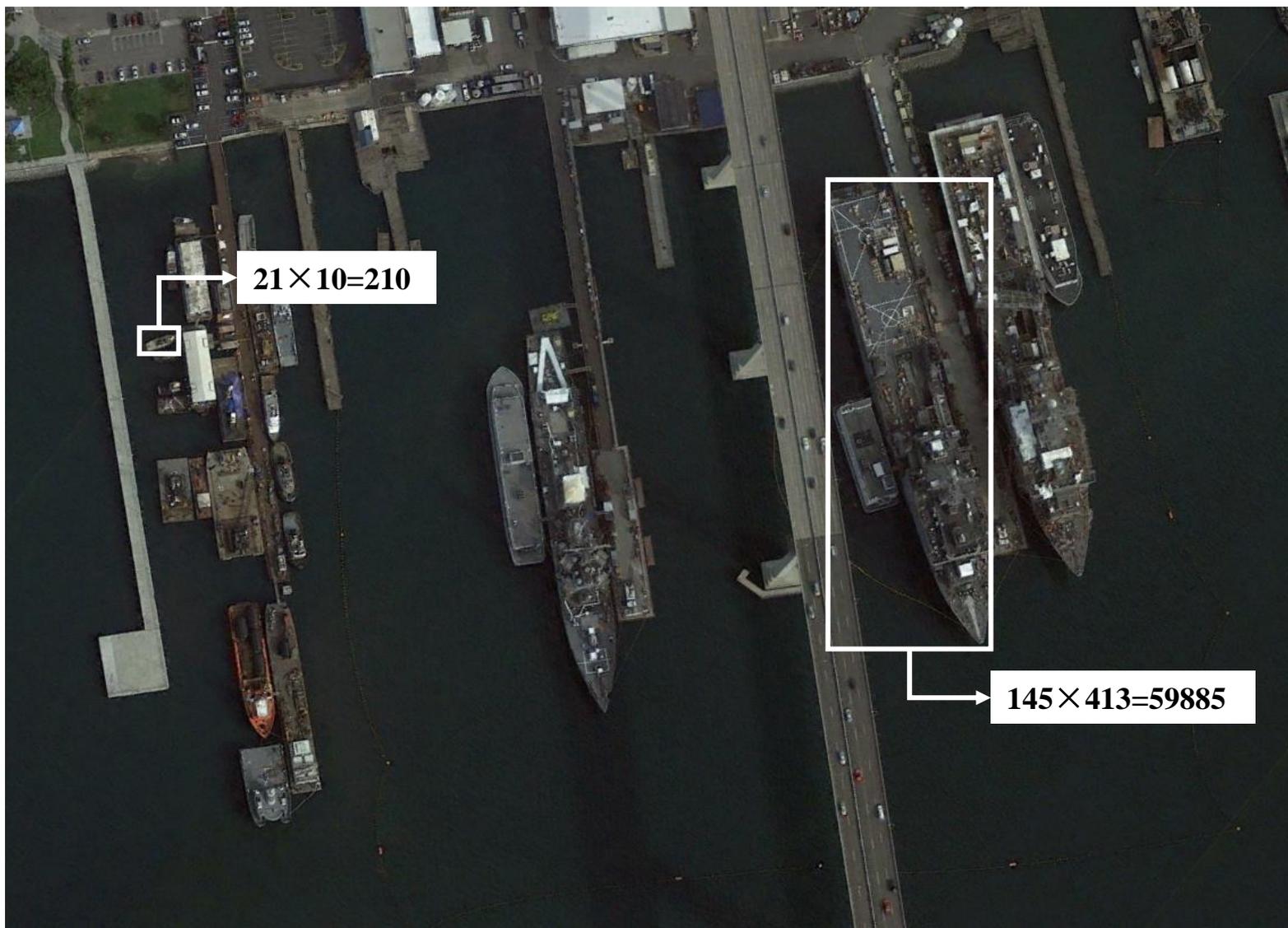
Pure scenario

## Optical Remote Sensing Image



Large size

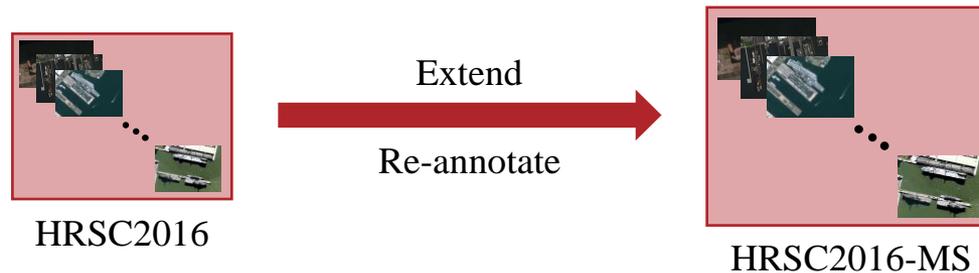
Complex scenario





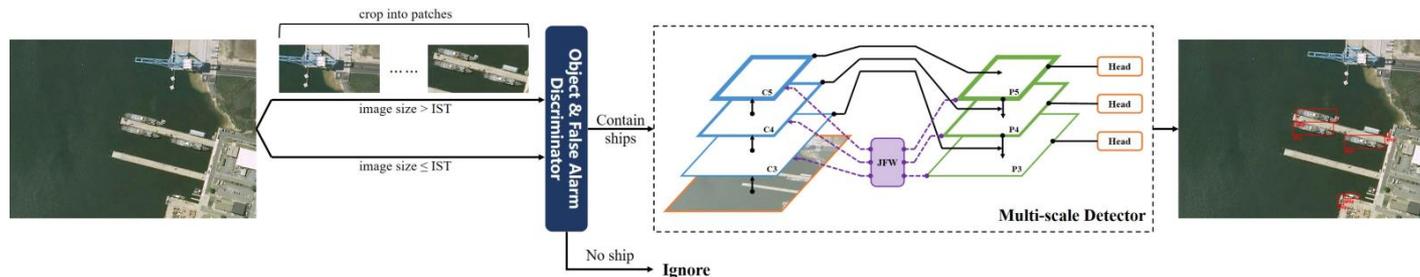
## DATASET

- We build a new dataset with rich multi-scale ship instances based on HRSC2016.



## ALGORITHM

- We propose **Adaptive Cropping Strategy** and **Objects and False Alarms Discriminator** to deal with the difficulty of size.
- We propose **Joint Recursive Feature Pyramid** to deal with the difficulty of scenario and multi-scale instances.

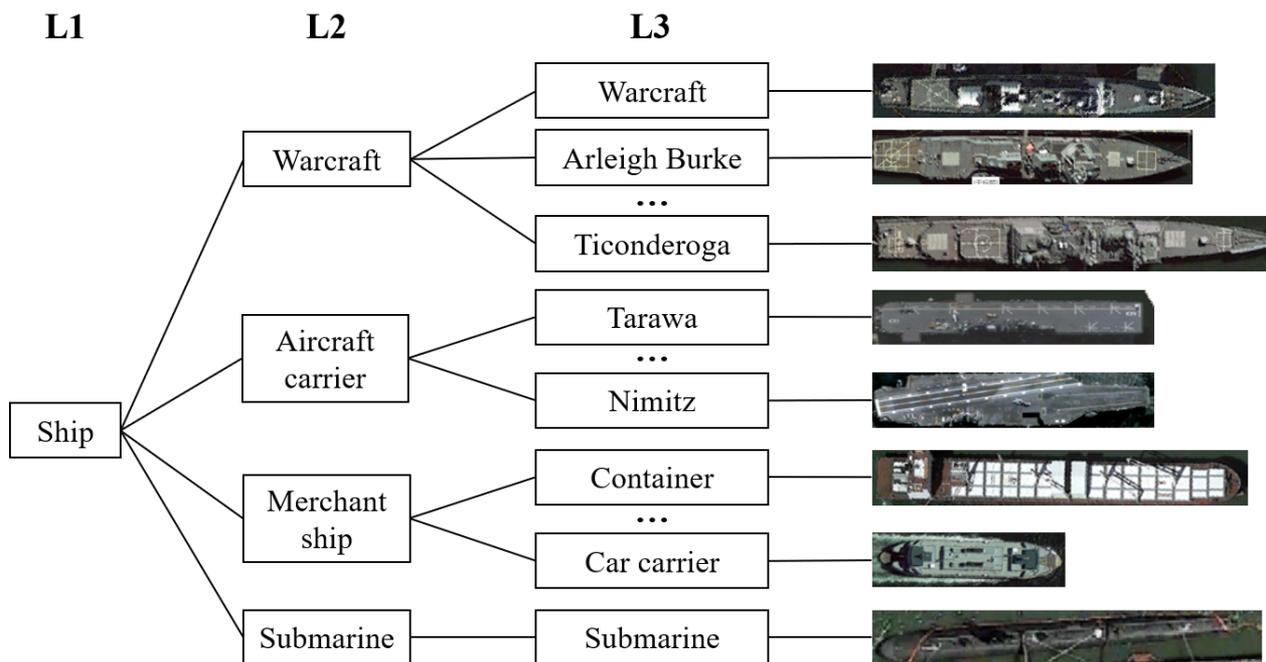




- Introduction
- **HRSC2016-MS Dataset**
- MSSDet
- Experimental Result
- Conclusion

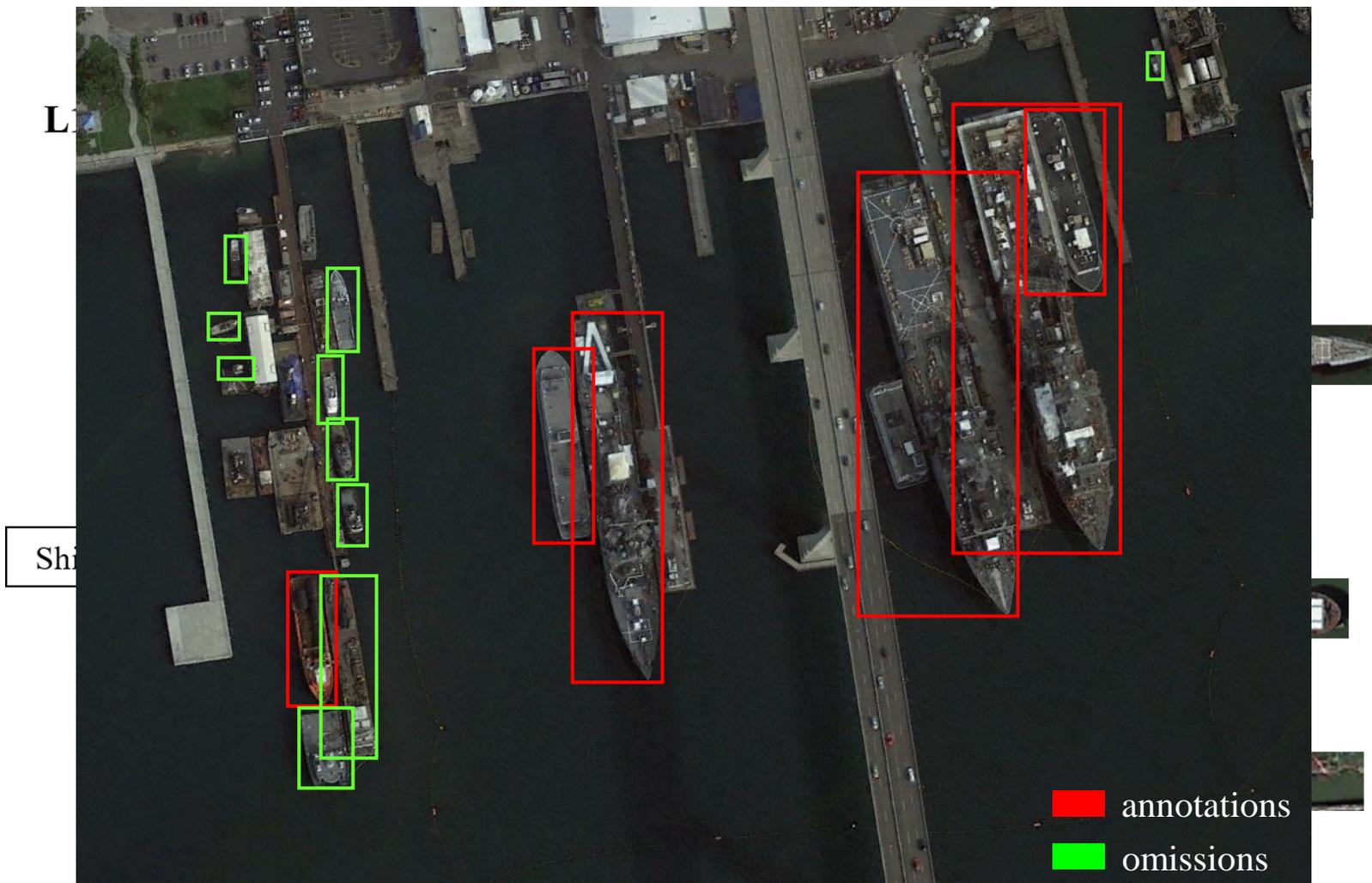


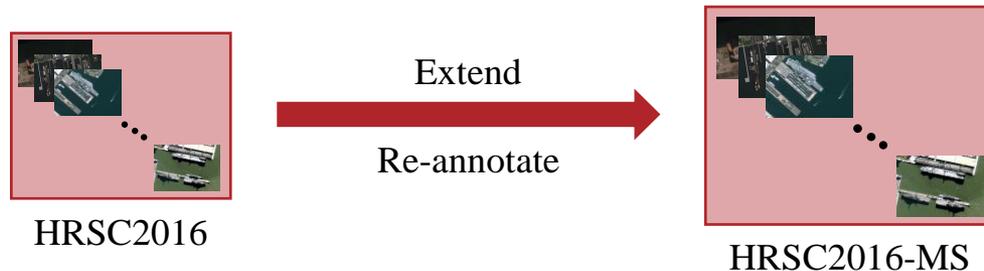
- **Data source:** Google Earth
- **Data volume:** 1070 images with 2976 ship instances
- **Image size:**  $300 \times 300$  to  $1500 \times 900$  (most of them are larger than  $1000 \times 600$ )
- **Spatial resolution:** between 2m and 0.4m
- **Scenario:** sea and sea-land
- **Annotation:** HBB and OBB
- **Label set:** cover 1, 4, 27 classes respectively.





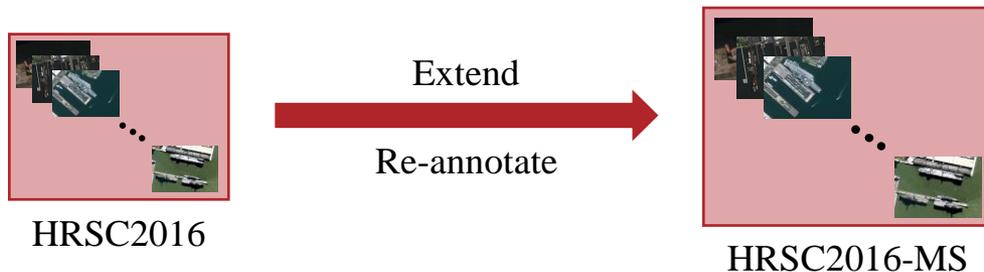
- **Defect 1:** the insufficiency of data
- **Defect 2:** annotation omission





## Extend

- **Data source:** Google Earth
- **Data volume:** 610 images
- **Image size:**  $300 \times 300$  to  $1500 \times 900$  (most of them are larger than  $1000 \times 600$ )
- **Spatial resolution:** between 2m and 0.4m
- **Scenario:** sea and sea-land



## Re-annotate

# HRSC2016-MS Dataset

## Annotation Method

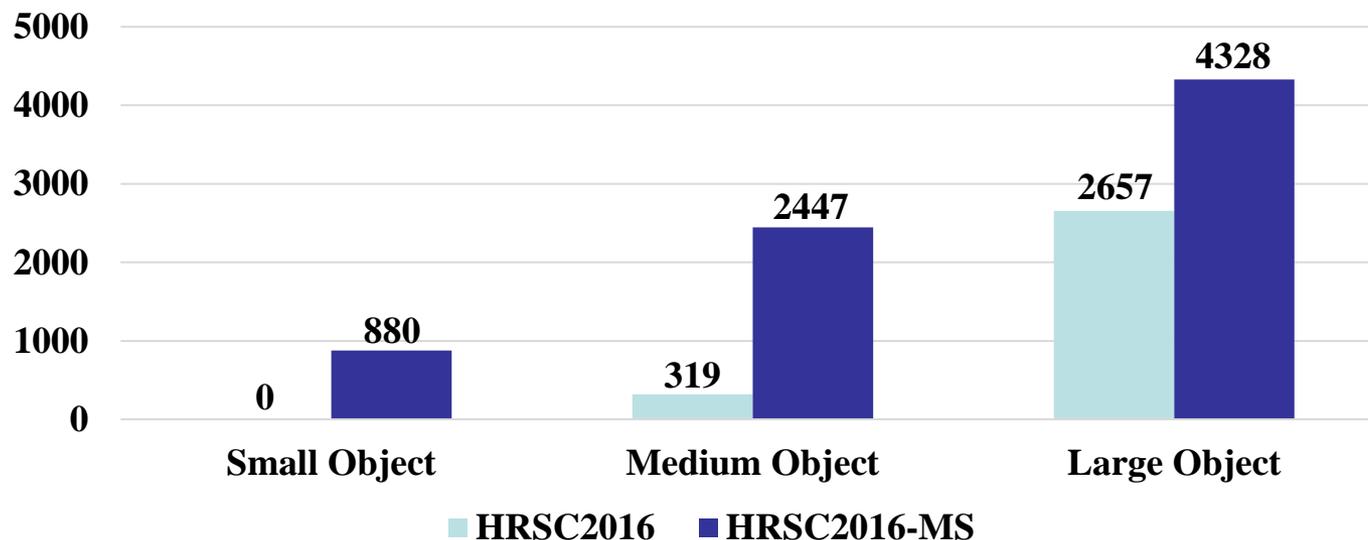


## HRSC2016

- **Data source:** Google Earth
- **Data volume:** 1070 images with 2976 instances
- **Image size:**  $300 \times 300$  to  $1500 \times 900$
- **Spatial resolution:** between 2m and 0.4m
- **Scenario:** sea and sea-land
- **Annotation:** HBB and OBB
- **Label set:** cover 1, 4, 27 classes respectively

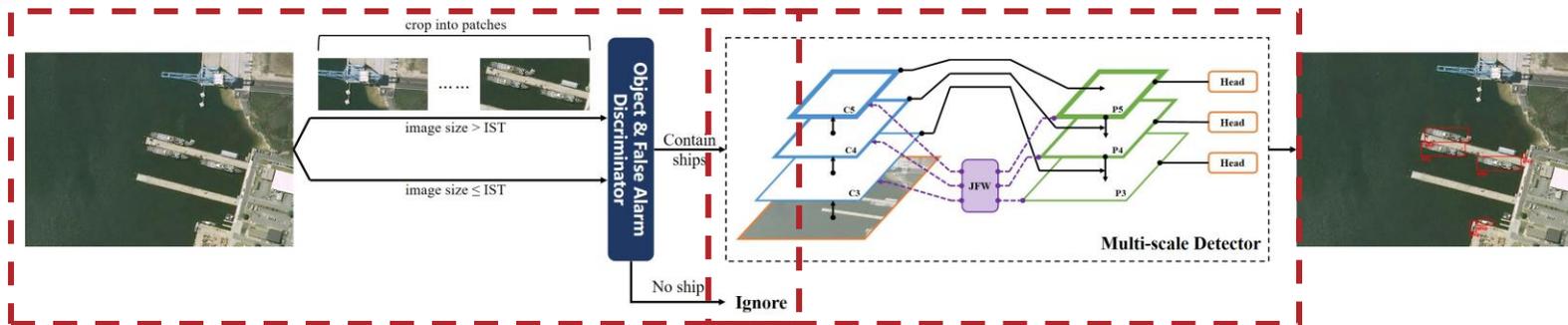
## HRSC2016-MS

- **Data source:** Google Earth
- **Data volume:** 1680 images with 7655 instances
- **Image size:**  $300 \times 300$  to  $1500 \times 900$
- **Spatial resolution:** between 2m and 0.4m
- **Scenario:** sea and sea-land
- **Annotation:** HBB and OBB
- **Label set:** cover 1 class

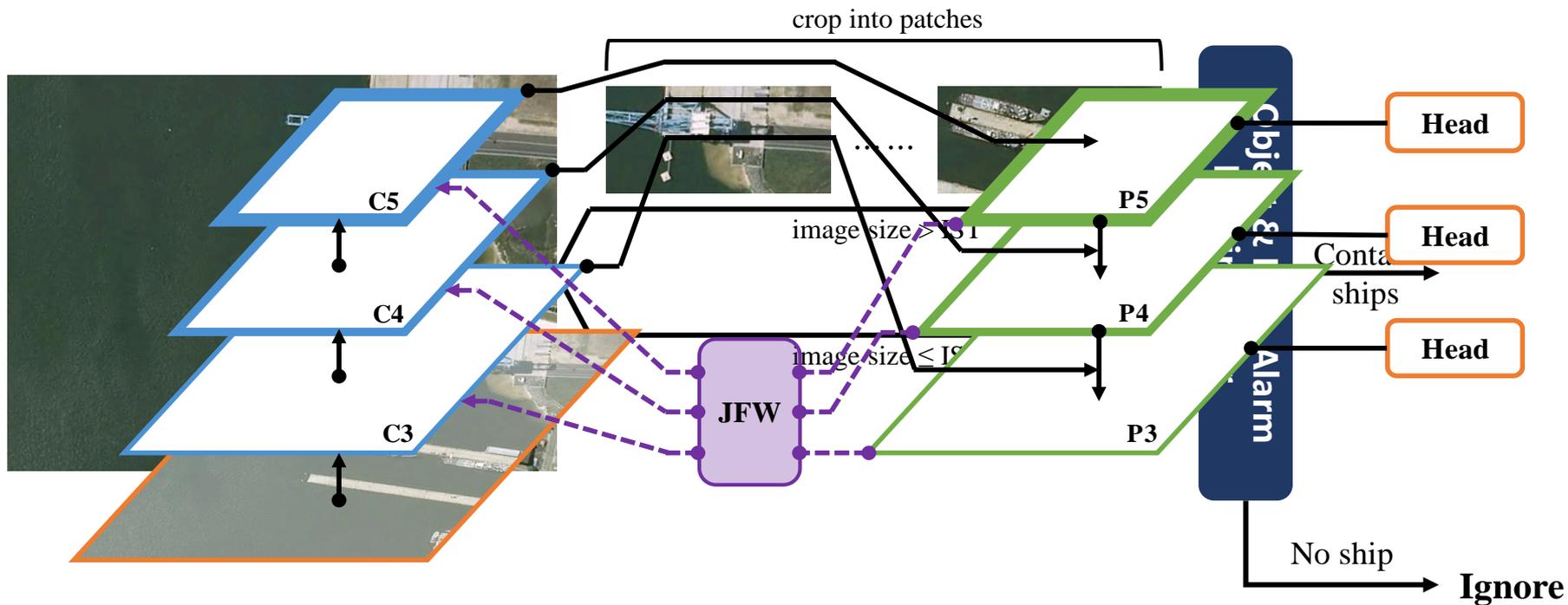




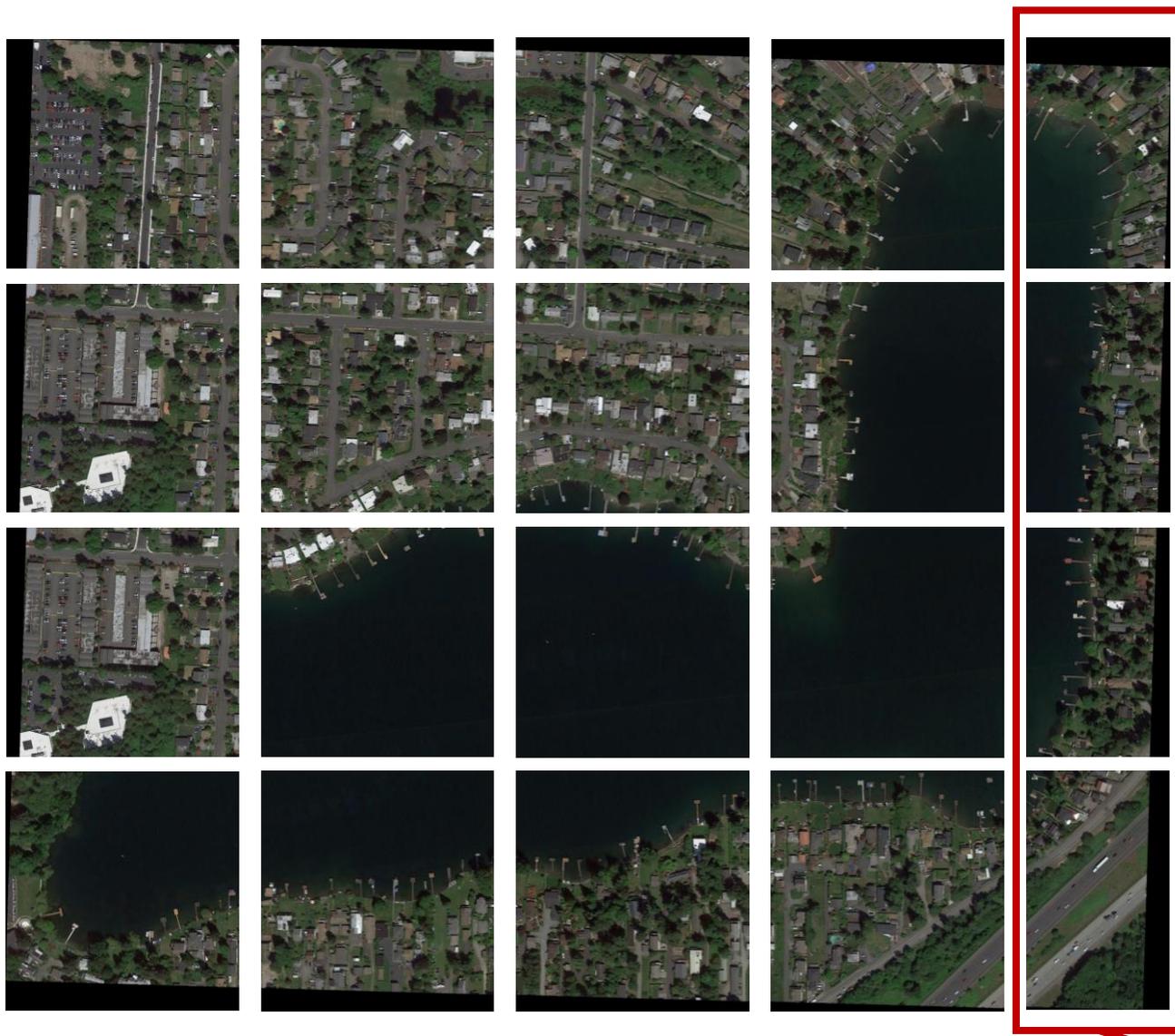
- Introduction
- HRSC2016-MS Dataset
- **MSSDet**
- Experimental Result
- Conclusion



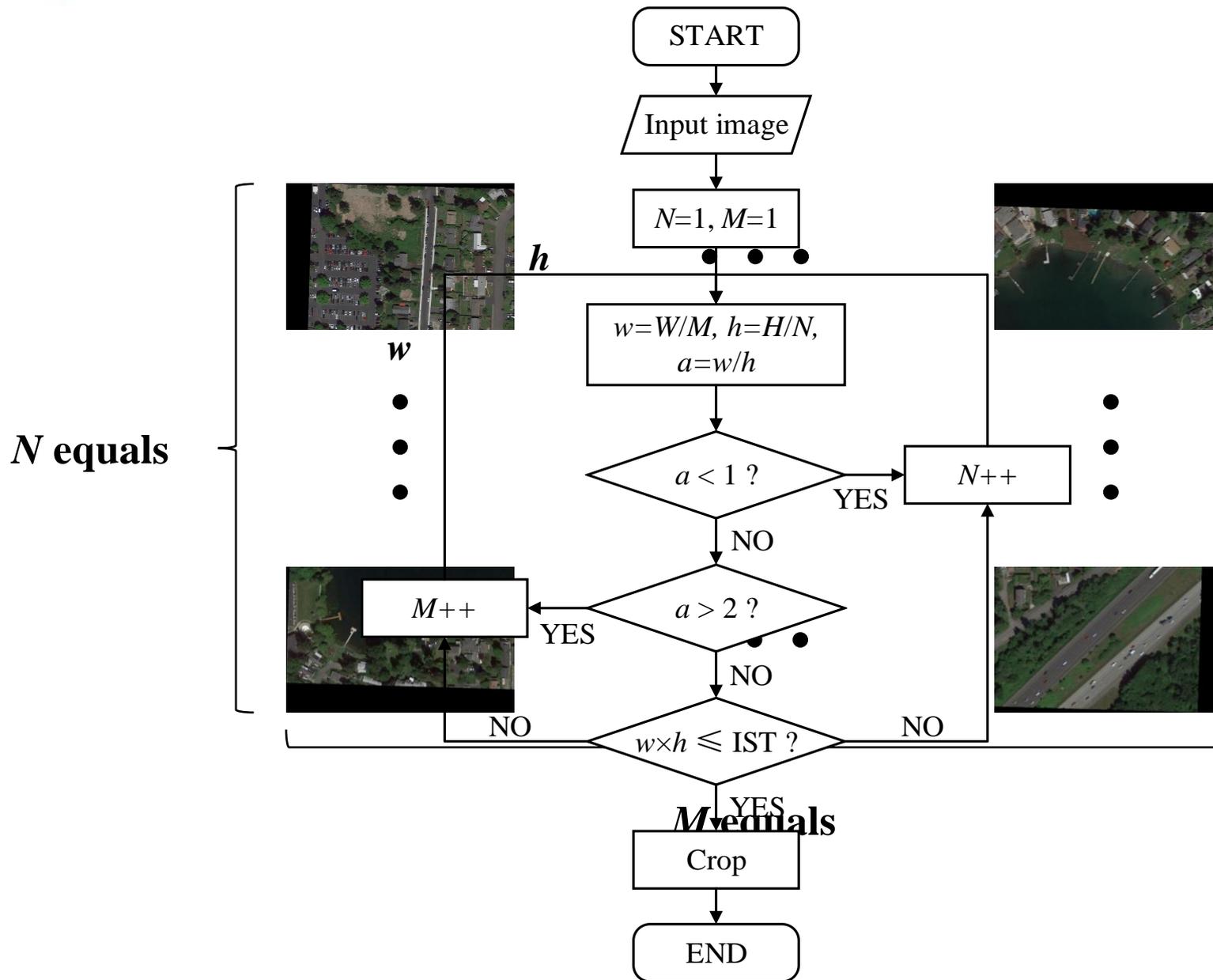
## Multi-scale detector







Unsuitable aspect ratio





## Blank Patch

- It is **waste of computing resources** when the detector is processing blank patches.
- It may **increase the risk of detecting false alarms** when input blank patches into the detector.



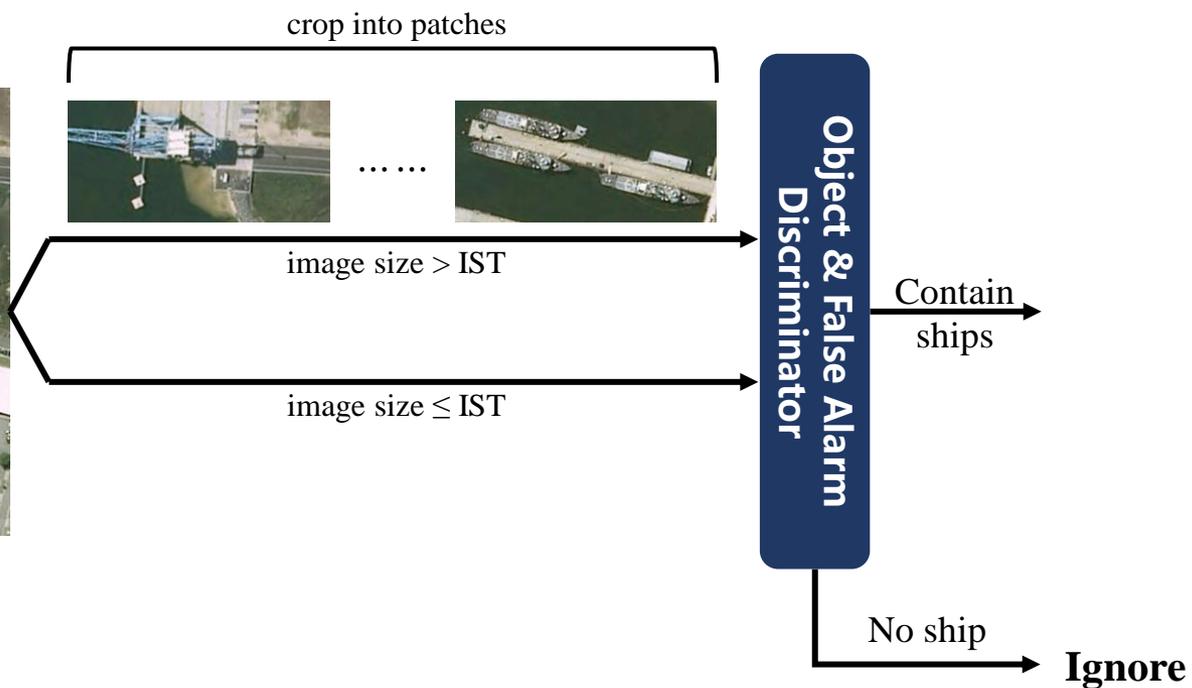
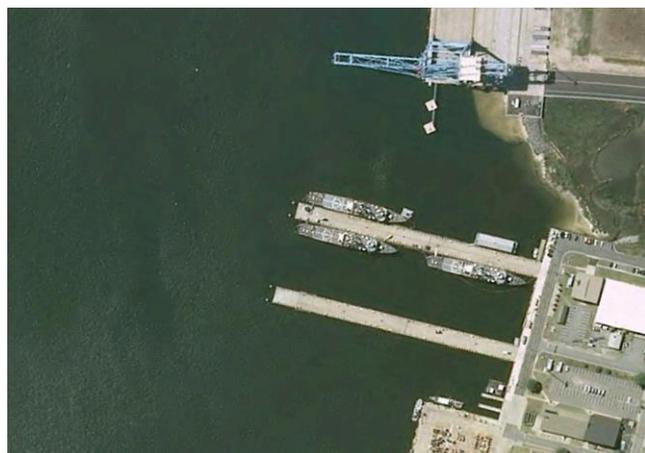
## ResNet34



layer name	architecture
conv1	conv, 7×7, 64, stride 2 max pooling, 3×3, stride 2
conv2	$\begin{bmatrix} 3 \times 3, 64 \\ 3 \times 3, 64 \end{bmatrix} \times 3$
conv3	$\begin{bmatrix} 3 \times 3, 128 \\ 3 \times 3, 128 \end{bmatrix} \times 4$
conv4	$\begin{bmatrix} 3 \times 3, 256 \\ 3 \times 3, 256 \end{bmatrix} \times 6$
conv5	$\begin{bmatrix} 3 \times 3, 512 \\ 3 \times 3, 512 \end{bmatrix} \times 3$
	global average pooling fc, 2-d softmax

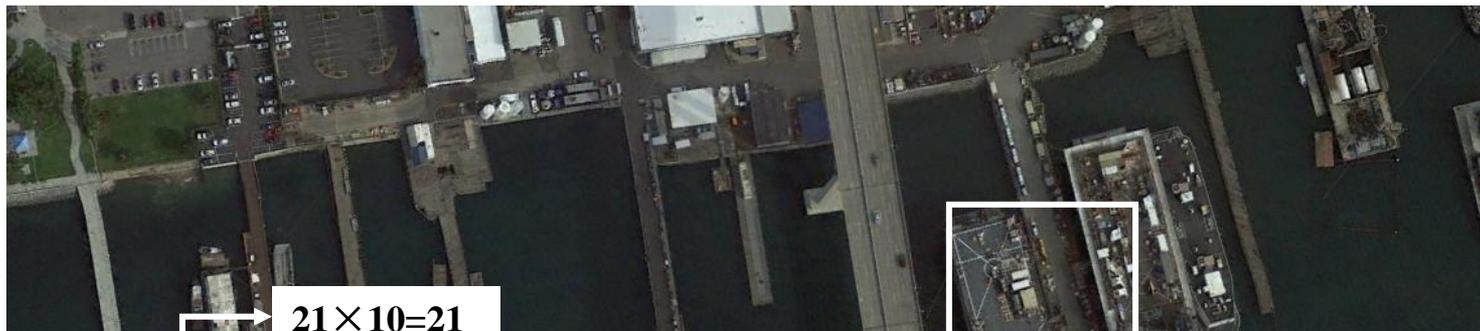
- OFAD act as a filter t
- A good OFAD should and **strong generaliz**

, **fast inference speed**

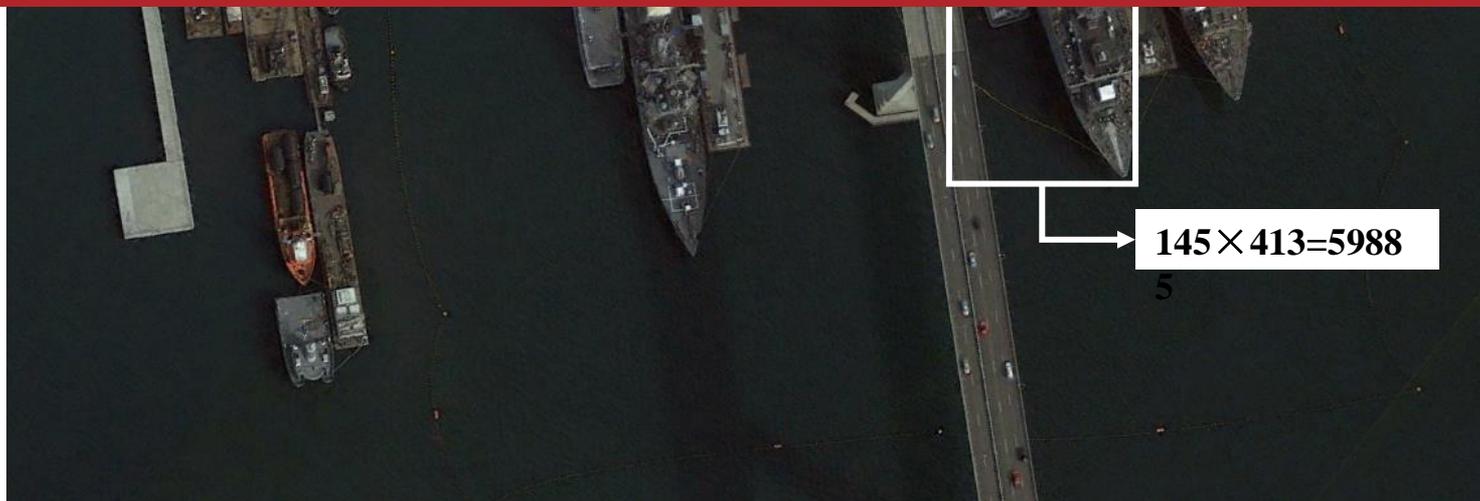




Learning the pattern of multi-scale objects is huge challenge



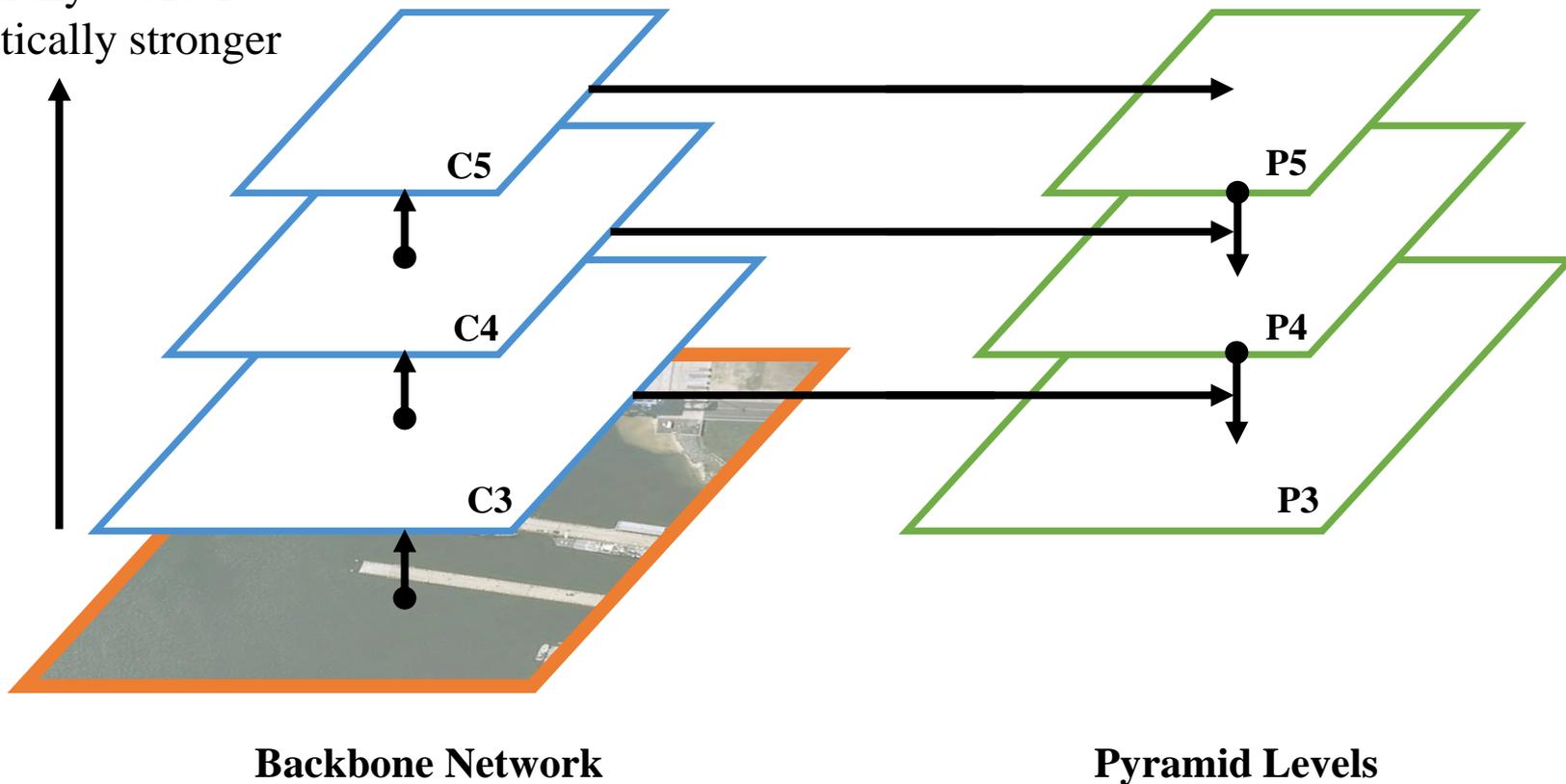
Improve multi-scale feature representation capability





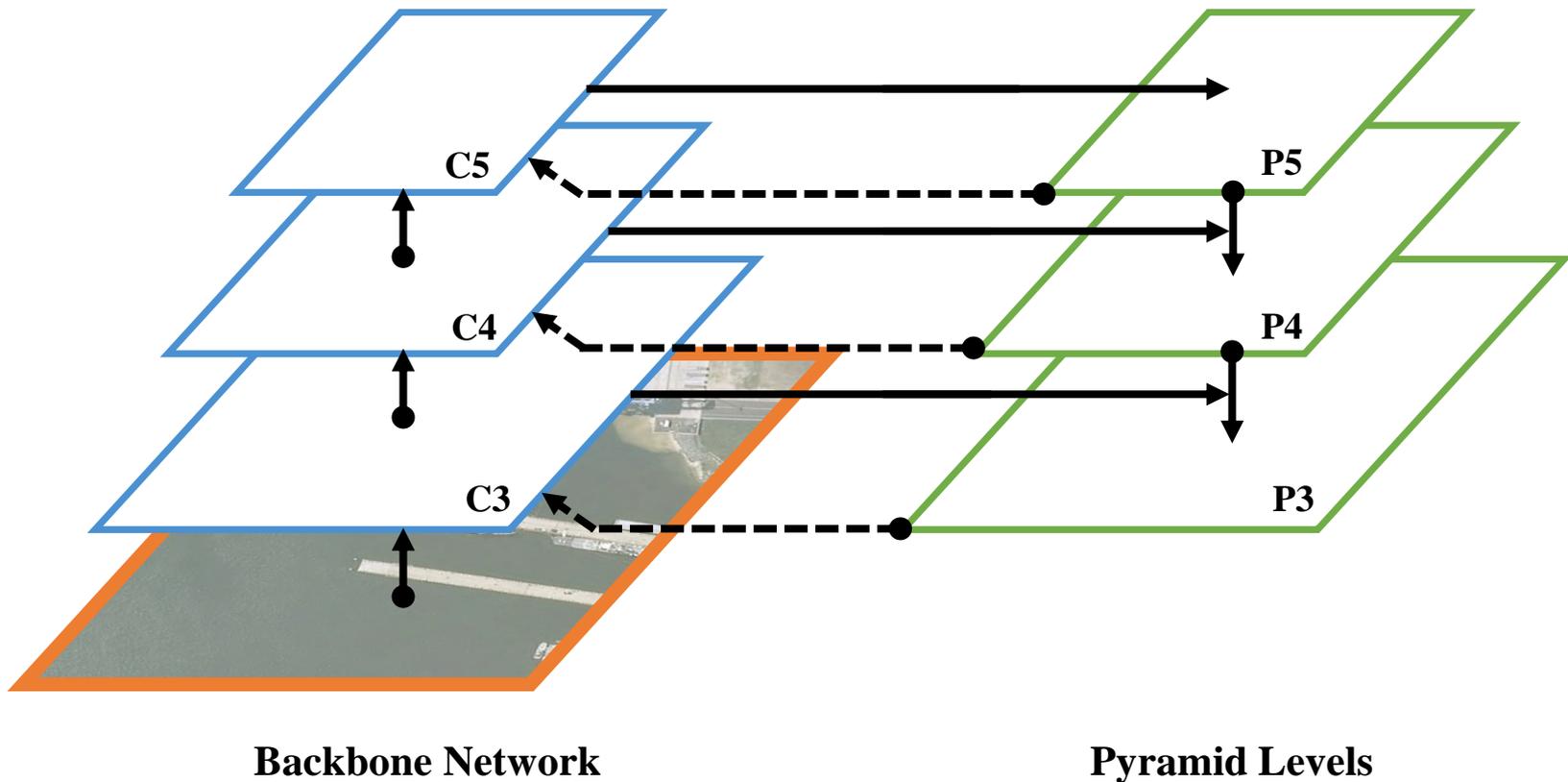
## Feature Pyramid Network (FPN)

spatially coarser  
semantically stronger





## Recursive Feature Pyramid (RFP)

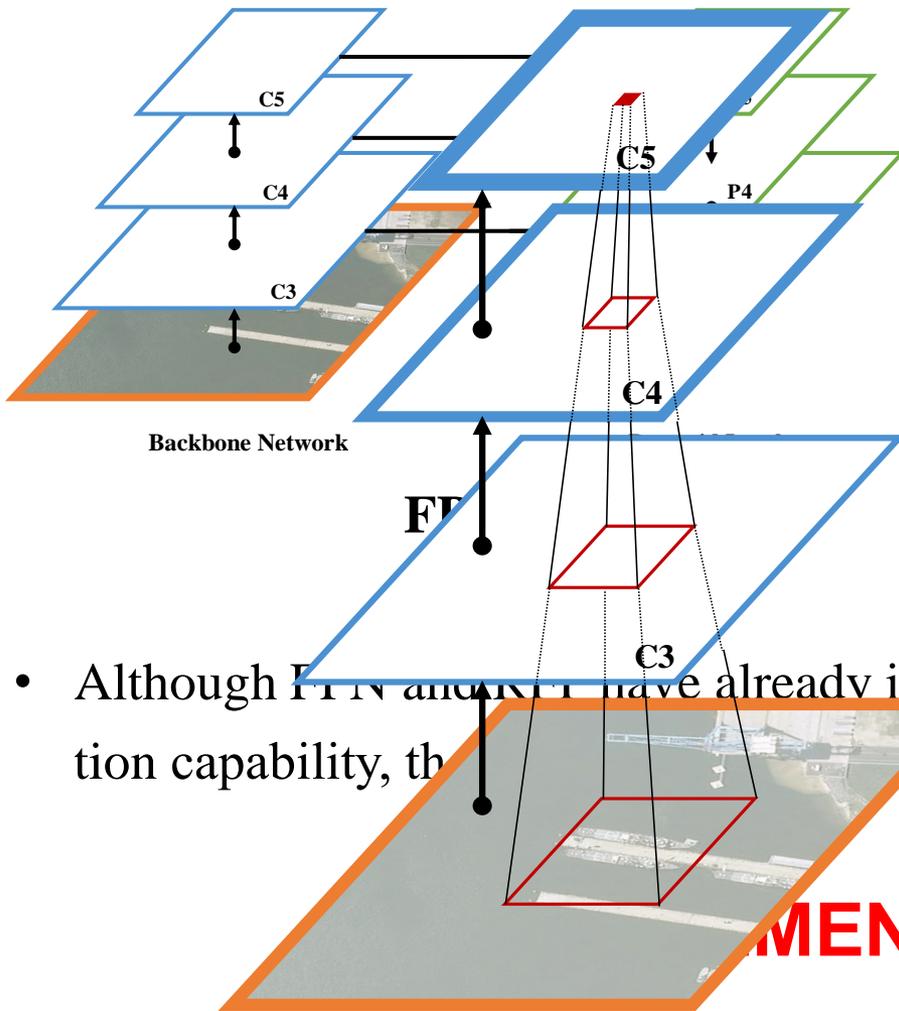


Backbone Network

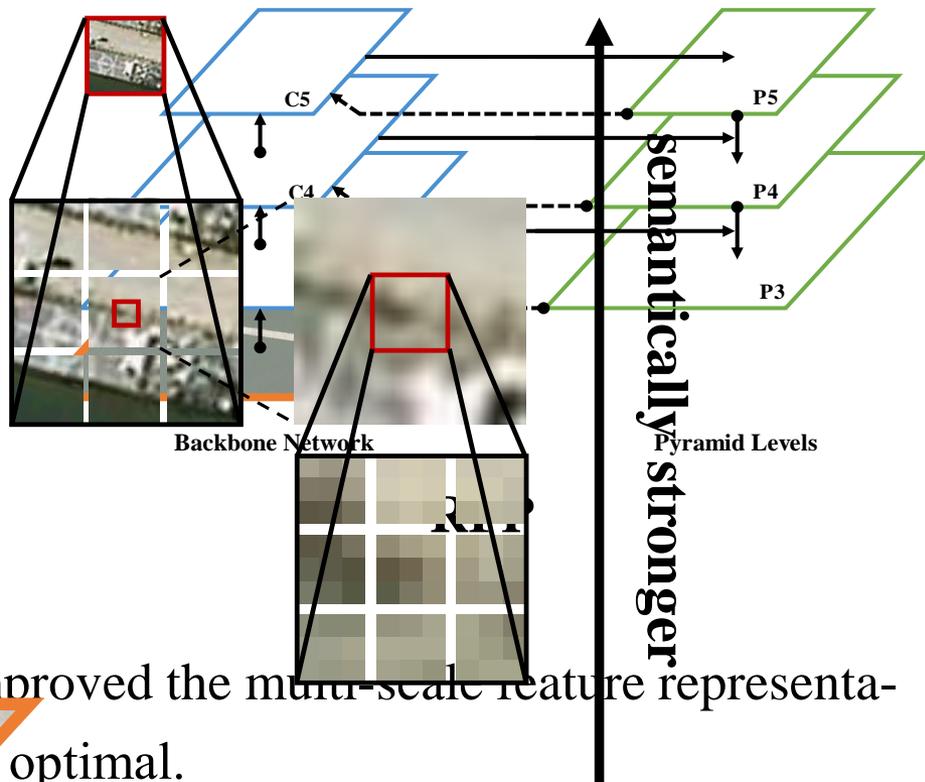
Pyramid Levels



### Backbone Network



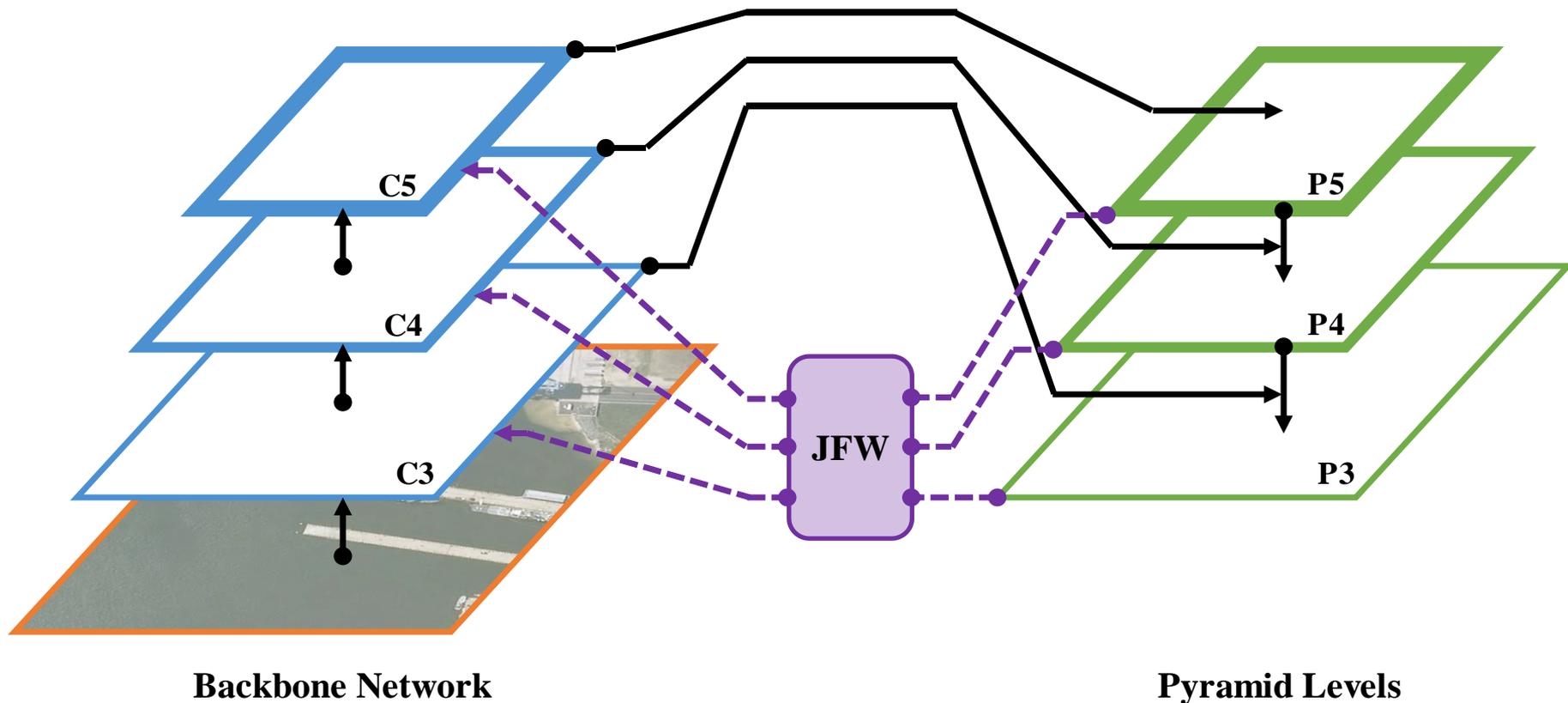
### Reception Field Visualization



- Although FPN and ANET have already improved the multi-scale feature representation capability, they are not optimal.

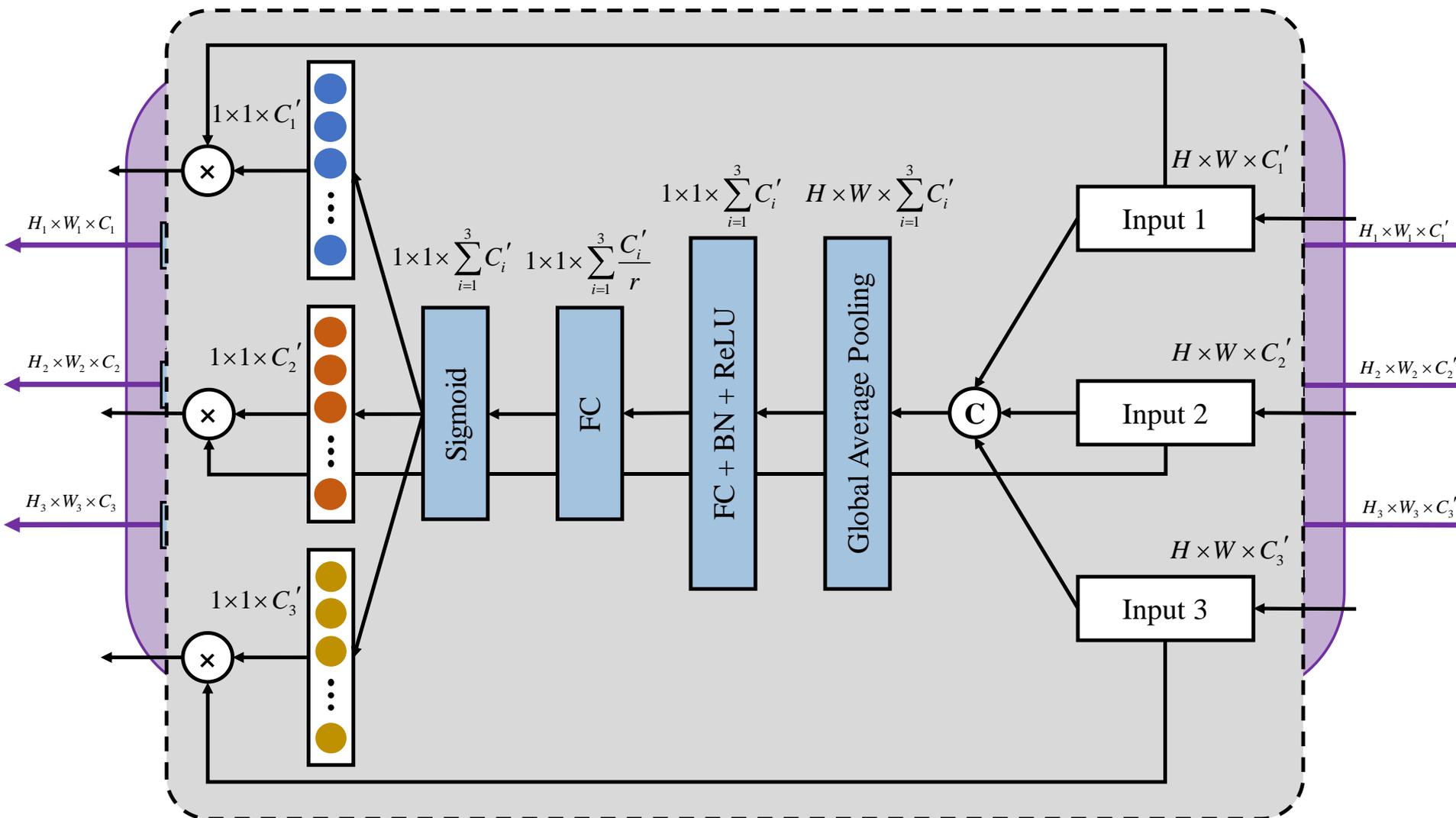


## Joint Recursive Feature Pyramid (JRFP)





## Joint Feedback Worker (JFW)





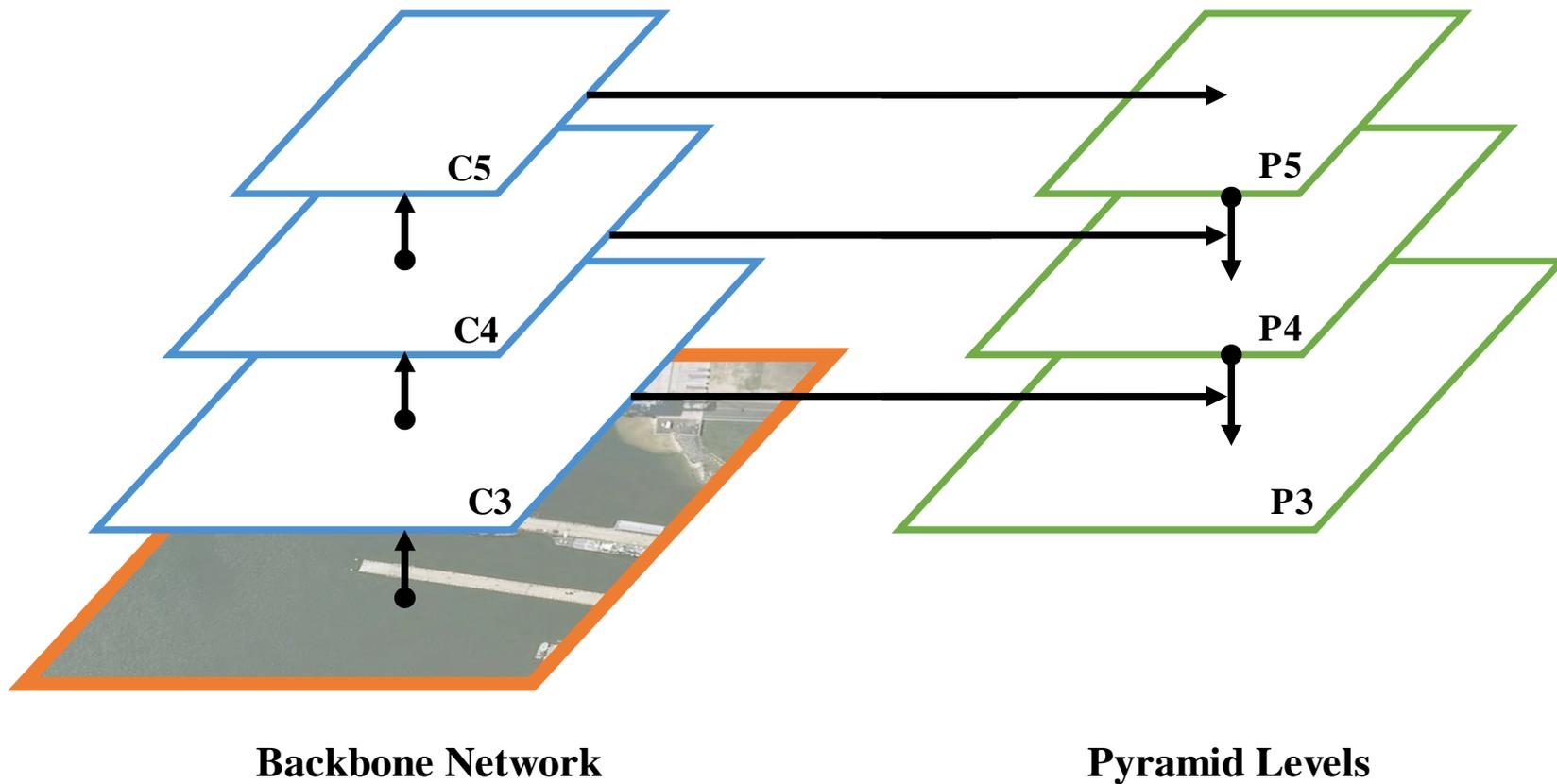
**Specificity** ← **BALANCE** → **Uniformity**



**Recursive Index (RI)**

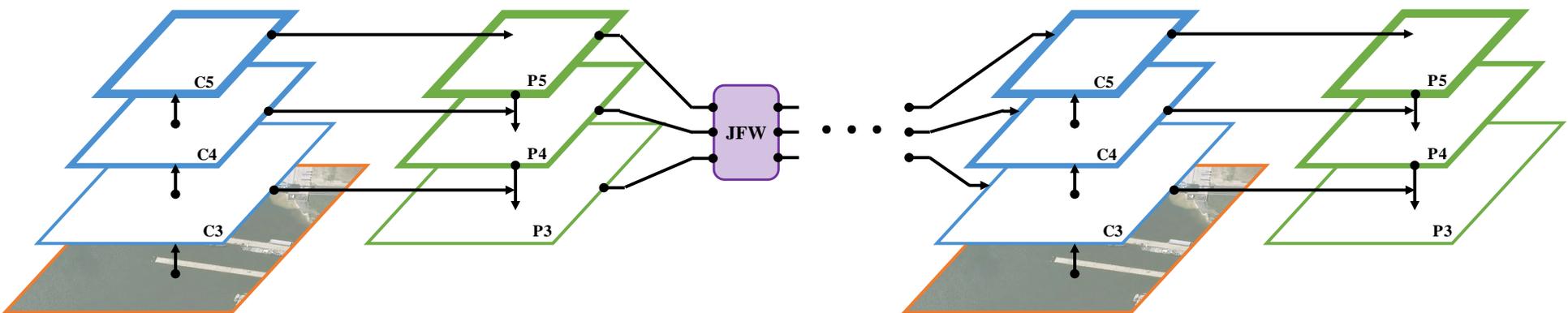


## Unrolled JRFP (RI=0)





## Unrolled JRFP (RI>0)





- Introduction
- HRSC2016-MS Dataset
- MSSDet
- **Experimental Result**
- Conclusion



Method	mAP (VOC2012 fashion)
Faster R-CNN [1]	0.246
Cascade R-CNN [2]	0.617
DetectoRS [3]	0.637
MSSDet (ours)	<b>0.721</b>

[1] S. Ren, et al. Faster R-CNN: Towards real-time object detection with region proposal networks. IEEE TPAMI, 2015.

[2] Z. Cai, et al. Cascade R-CNN: Delving into High Quality Object Detection. CVPR, 2018.

[3] S. Qiao, et al. DetectoRS: Detecting Objects with Recursive Feature Pyramid and Switchable Atrous Convolution. arXiv:2006.02334, 2020



Method	mAP (VOC2012 fashion)
BL1 [1]	0.797
Faster R-CNN (soft NMS) [2]	0.845
Faster R-CNN (dilated conv) [3]	0.709
Cascade R-CNN [4]	0.904
DectetoRS [5]	0.920
<b>MSSDet (ours)</b>	<b>0.946</b>

[1] Z. Liu, et al. A High Resolution Optical Satellite Image Dataset for Ship Recognition and Some New Baselines. ICPRAM, 2017.

[2] X. Tan, et al. Inshore ship detection based on improved faster R-CNN. Proc. SPIE 11429, MIPPR 2019.

[3] S. Wei, et al. Ship Detection in Remote Sensing Image based on Faster R-CNN with Dilated Convolution. Proceedings of the 39<sup>th</sup> Chinese Control Conference, 2020

[4] Z. Cai, et al. Cascade R-CNN: Delving into High Quality Object Detection. CVPR, 2018.

[5] S. Qiao, et al. DectetoRS: Detecting Objects with Recursive Feature Pyramid and Switchable Atrous Convolution. arXiv:2006.02334, 2020



	Method	mAP (VOC2012 fashion)	
	R-CNN	0.377	
TAS	RICNN	0.442	
SZT	RICAOD	0.509	
NW	RIFD-CNN	0.561	
VEL	Faster R-CNN	0.651	
UC	SSD	0.586	
DLE	YOLOv3	0.571	
HRS	Mask R-CNN	0.652	
RSC	RetinaNet	0.661	
DO	PANet	0.661	
DIO	CornerNet	0.649	
HRF	MSSDet (ours)	<b>0.778</b>	



Method	mAP (VOC2012 fashion)
MSSDet (RI=0)	0.660
MSSDet (RI=1)	0.667
MSSDet (RI=2)	<b>0.721</b>
MSSDet (RI=3)	0.674

\*: The ablation study was done on HRSC2016-MS dataset

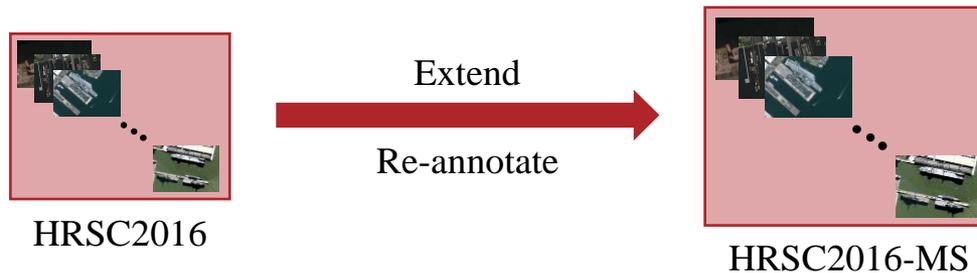


- Introduction
- HRSC2016-MS Dataset
- MSSDet
- Experimental Result
- **Conclusion**



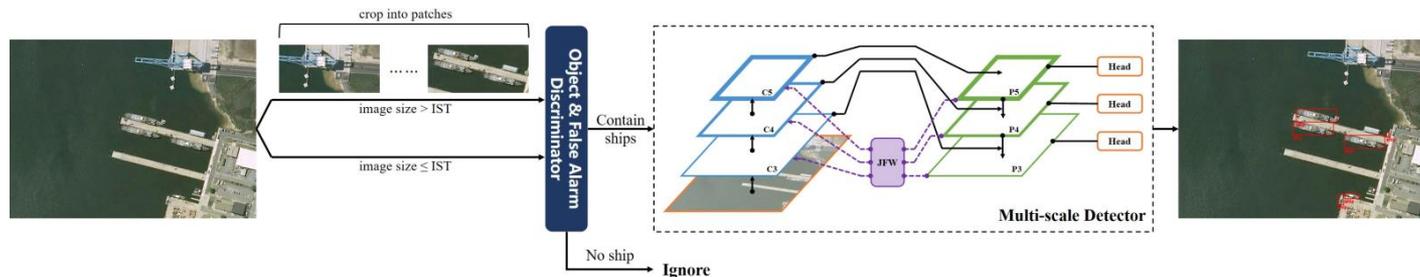
## DATASET

- We build a new dataset with rich multi-scale ship instances based on HRSC2016.



## ALGORITHM

- We propose **Adaptive Cropping Strategy** and **Objects and False Alarms Discriminator** to deal with the difficulty of size.
- We propose **Joint Recursive Feature Pyramid** to deal with the difficulty of scenario and multi-scale instances.





西安电子科技大学  
XIDIAN UNIVERSITY

# THANKS FOR LISTENING

Q & A